Meeting - March 30th

Accomplished

Notes:

1. Wilson’s team is using a method to calculate pose of the camera
2. Pull GPS location where the plane is at from the Pixhawk subsystem and apply coordinate transformation/use euler angles to determine corrected angle

In Progress:

Next Steps:

1. Develop detailed flight test plan for Friday quadcopter flight test using ASE Team framework
2. Set up Raspberry Pi and HQC on quadcopter
3. Explore options for using damper to minimize vibrational effects from rotors and impact on resolution
4. Work on RGB threshold algorithms and develop working prototype; it is desirable for us to work on the Haar Cascade algorithms later in the project

Questions/Concerns:

1. Is the meeting with Wilson recorded and if so where can it be accessed?